Processes

"Heavy weight" control flow

- Context switch
 - Non negligible cost
 - A lot of data to be saved/restored
 - Cause cache miss and TLB miss (see virtual memory lecture)
- Isolated address space
 - Sharing data is painful
 - Shared memory
 - Message passing
- Thread concept

Thread concept

Lightweigh process

- Light context
- A shared part : memory, open file ...
- A private part : stack, registers, ...

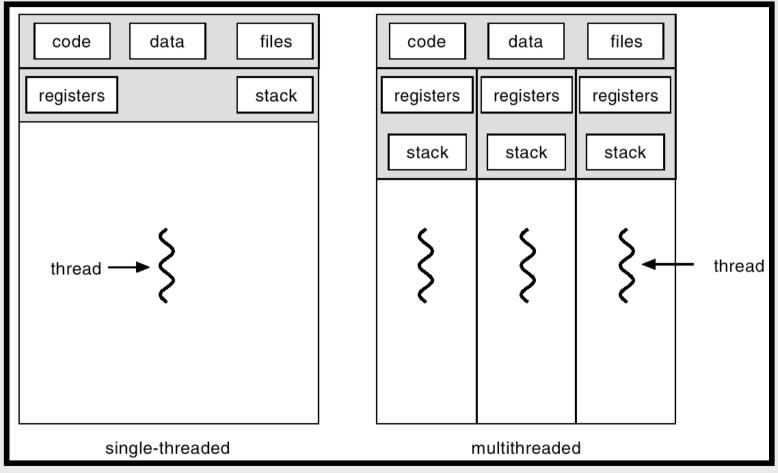
Schedulable execution context

More efficient context switch

Ease the programming of concurent applications

- Multiple execution flow in a same adress space
- Immediate data sharing
- Simple programs use one thread per process
- But can also have multi-threaded programs
- Multiple threads running in same process's address space

Single-threaded et multi-threaded Process





Why Thread

Responsiveness

- Do not block the whole program when only a part of it should be blocked
- Allows program to overlap I/O and computation (same benefit as OS running emacs & gcc simultaneously)

Resource sharing

- Lighter-weight abstraction than processes (IPC, shmem)
- All threads in one process share memory, file descriptors, etc

Economy

Allocating memory, resources and context switching for process is costly

Scalability

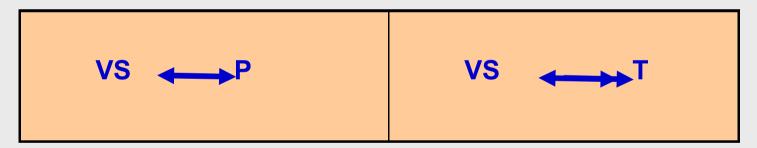
- A single process can only use a single CPU at a time
- Allows one process to use multiple CPUs or cores

Thread history

Adress Space

Execution flow

- 2 notions tied together with the process concept
- Threads dissociate these two notions



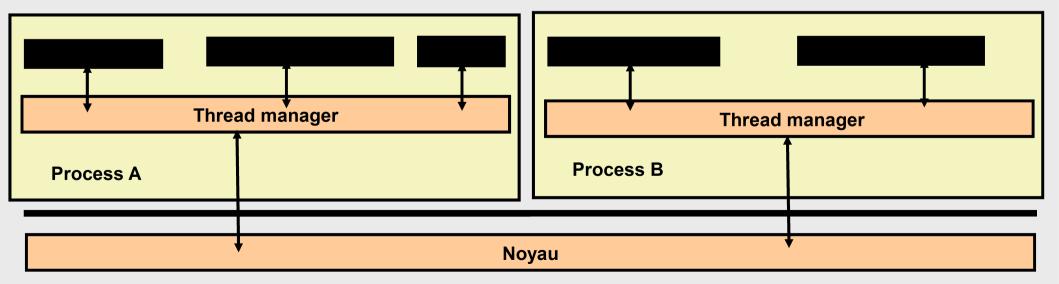
Differents kind of thread

- User-level threads
- Kernel-supported
- Mixed solutions

User-level Threads

- Implemented in a user level library
- Unmodified Kernel
- Threads and thread scheduler run in the same user process

Examples: POSIX Pthreads, Mach C-threads, Solaris threads



Advantages and disadvantage of Userlevel threads

Parallelism (-)

No real parallelism between the threads within a process

Efficiency (+)

Quick context switch

Blocking system call (-)

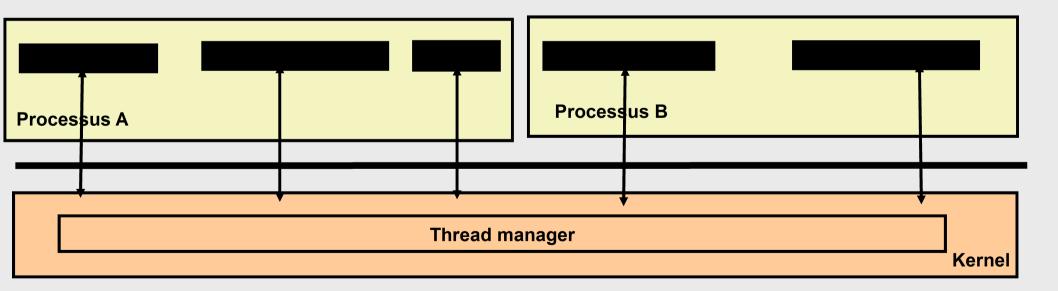
- The process is blocked in the kernel
- All thread are blocked until the system call (I/O) is not terminated

Threads kernel-supported

Thread managed by the kernel

- Thread creation as a system call
- When a thread is blocked, the processor is allocated to another thread by the kernel

Examples: Windows NT/2000, Solaris, Tru64 UNIX, Linux



Kernel-supported pro and cons

Blocking system call (+)

 When a thread is blocked dur to a SVC call, the tread in the same virtual space are not

Real Parallelism (+)

N threads in the same virtual space can run on K processors

Efficiency (-)

- More expensive context switch / user level threads
 - Every management operation goes throught the kernel
 - Require more memory

Hybrid solution for light context switch (sol 1)

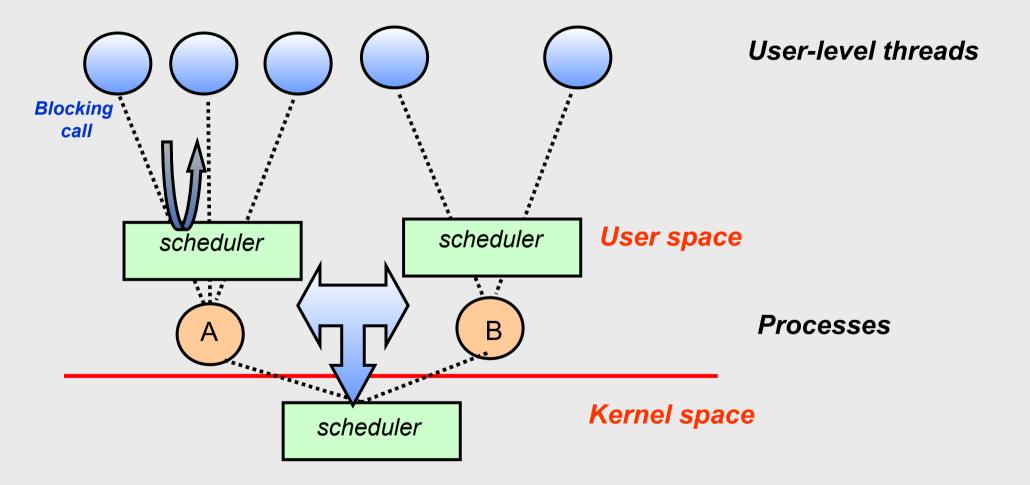
Take the best of the above implementations

- Light context switch of user level thread
- Avoid blocking all threads when invoking a system call
- Follows the principles of user level threads
 - Context switch managed at user level

Kernel modification to manage system call to avoid blocking

- When a thread uses a blocking svc, the kernel does not preempt the processor
- Signals used to managed the end to the blocking svc
- Two cooperating scheduler : user and system level

Hybrid solution for light context switch



Hybrid solution for light context switch to enable real parallelism (sol 2)

User threads implemented on kernel threads

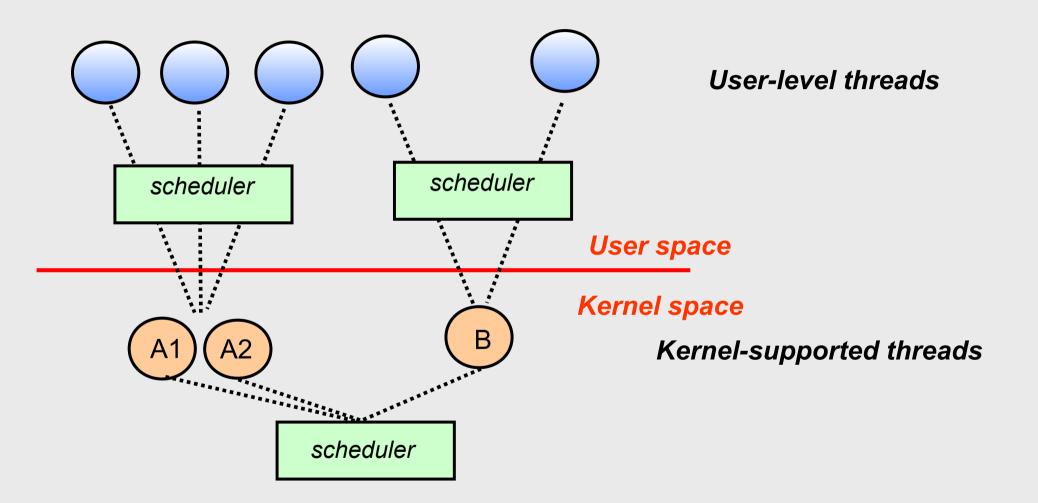
- Multiple kernel level threads per process
- Thread creation, destruction still library fonctions

Sometimes called n:m threading

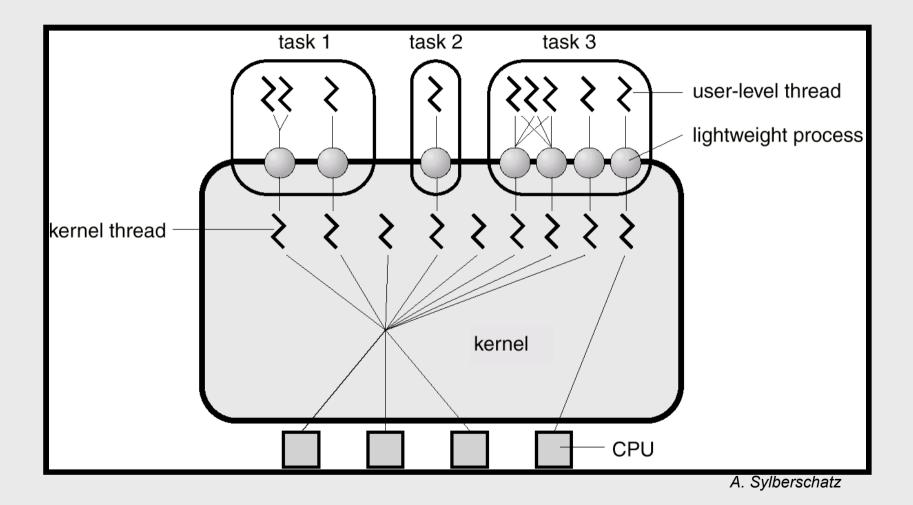
- Have n user threads per m kernel threads
- (simple user level threads are n:1, kernel thread are 1:1)

A pool of user threads mapped on a pool of kernel threads

Hybrid solution for light context switch to enable real parallelism (sol 2)



Tread model : many to many

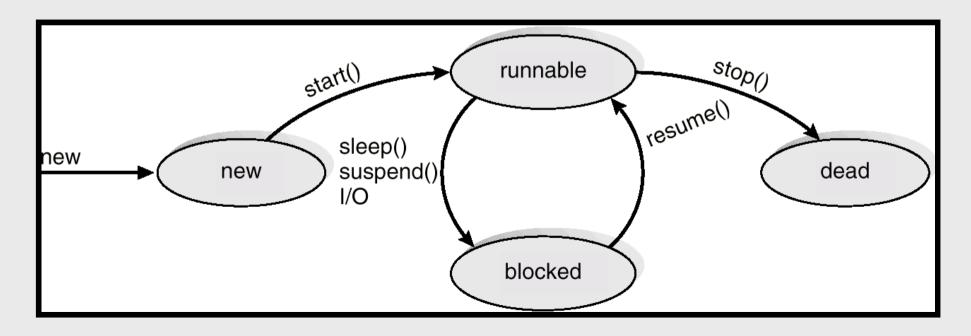


Threads Java

User-level / Kernel-supported, depending on the JVM implementation

Creation

- Thread class extension
- Implementation of the Runnable interface



POSIX Threads : Pthreads API

- int thread create (tid, attr, void (*fn) (void *), void *);
 - Create a new thread, run fn with arg
- void thread exit ();
 - Destroy current thread
- void thread join (tid thread);
 - Wait for thread thread to exit
- Plus lots of support for synchronization [next week]

Posix thread creation

```
int pthread_create (
    pthread_t *tid,
    pthread_attr *attr,
    void* (*start_routine)(void *),
    void *arg);
```

- Create a thread
- Run the start_fct with arg as arguments
- Tid : Id of the created thread

Example 1/2

```
#include <pthread.h>
```

```
void * ALL_IS_OK = (void *)123456789L;
```

```
char *mess[2] = { "thread1", "thread2" };
```

```
void * writer(void * arg)
{ int i, j;
```

```
for(i=0;i<10;i++) {
    printf("Hi %s! (I'm %lx)\n", (char *) arg, pthread_self());
    j = 800000; while(j!=0) j--;
}</pre>
```

```
return ALL_IS_OK;
}
```

Example 2/2

```
int main(void)
{ void * status;
 pthread t writer1 pid, writer2 pid;
  pthread create(&writer1 pid, NULL, writer, (void *)mess[1]);
  pthread create(&writer2 pid, NULL, writer, (void *)mess[0]);
  pthread join(writer1 pid, &status);
   if (status == ALL IS OK)
      printf("Thread %lx completed ok.\n", writer1 pid);
  pthread join(writer2 pid, &status);
   if (status == ALL IS OK)
      printf("Thread %lx completed ok.n", writer2 pid);
   return 0;
```

Fork(), exec()

- What happens if one thread of a program calls fork()?
 - Does the new process duplicate all threads ? Or is the newprocess single-threaded ?
 - Some UNIX systems have chose to have two versions of fork()
- What happens if one thread of a program calls exec()?
 - Generally, the new program replace the entire process, including all threads.

Critical section problem

```
int count = 0;
void loop(void *ignored) {
 int i;
 for (i=0; i<10; i++) count++;
}
int main () {
 tid id = thread create (&tid, NULL,loop, NULL);
 loop (); thread_join (id);
 printf("%d",count);
}
```

What is the output of this program ?

Critical section problem

- Need solution to critical section problem
 - Place count++ in critical section
- Protect critical sections from concurrent execution
 - n processes all competing to use some shared data
 - Each process has a code segment, called critical section, in which the shared data is accessed.
- Problem ensure that when one process is executing in its critical section, no other process is allowed to execute in its critical section.

Desired properties

- Mutual Exclusion
 - Only one thread can be in critical section at a time
- Progress
 - Say no process currently in critical section (C.S.)
 - One of the processes trying to enter will eventually get in
- Bounded waiting
 - Once a thread T starts trying to enter the critical section, there is a bound on the number of times other threads get in

Mutual exclusion (next lecture)

- pthread_mutex_t : lock type
- pthread_mutex_init : lock init
- pthread_mutex_lock : lock the mutex
- pthread_mutex_unlock : unlock the mutex

```
pthread_mutex_t mon_mutex;
pthread_mutex_init(&mon_mutex,NULL);
pthread_mutex_lock(&mon_mutex);
... critical section
pthread_mutex_unlock(&mon_mutex);
//fin du programme
pthread mutex_destroy(&mon_mutex);
```

Conditions (next lecture)

- pthread_cond_t : condition type
- pthread_cond_init : condition initialization
- pthread_cond_wait : block the thread on a condition and unlock the mutex
- pthread_cond_signal: wake the thread on the condition et relock the mutex

Beware the signaled thread do not take control immediately ...